Scheduling in Linux

Logistics

- 1. HW4 deadline: 3/23 (right after spring break)
- 2. No TA support for HW4 during spring break
- 3. This Thursday 3/6 Midterm Review (solve together past midterms)
- 4. Next Tuesday 3/11 NO CLASS
- 5. Next Thursday 3/13 In-class Midterm

Real-time scheduling

□ Hard real-time

- complete critical task within guaranteed time period
- Soft real-time
 - critical processes have priority over others

Linux supports soft real-time

Linux: multi-level queue with priorities

- Soft real-time scheduling policies
 - SCHED_FIFO (FCFS)
 - SCHED_RR (round robin)
 - Priority over normal tasks
 - 100 static priority levels (1..99)
- Normal scheduling policies
 - SCHED_NORMAL: standard
 - · SCHED_OTHER in POSIX
 - SCHED_BATCH: CPU bound
 - SCHED_IDLE: lower priority
 - Static priority is 0
 - 40 dynamic priority
 - "Nice" values

sched_setscheduler(), nice()

See "man 7 sched" for detailed overview



Linux scheduler history

- \Box O(N) scheduler up to 2.4
 - Simple: global run queue
 - Poor performance on multiprocessor and large N
- □ O(1) scheduler in 2.5 & 2.6
 - Good performance: per-CPU run queue
 - Complex and error prone logic to boost interactivity
 - No fairness guarantee
- Completely Fair Scheduler (CFS) in 2.6 and later
 - Currently default scheduler for SCHED_NORMAL
 - Processes get fair share of CPU
 - Naturally boosts interactivity
- □ Alternative schedulers: BFS, MuQSS, PDS, BMQ, TT, etc.
 - <u>https://wiki.archlinux.org/title/improving_performance#Alternative_CPU_</u> <u>schedulers</u>

Infinitesimally small time slice n processes: each runs uniformly at 1/nth rate

1/3rd progress

- Various approximations of the ideal
 - Lottery scheduling
 - Stride scheduling
 - Linux CFS

•3 Processes

Completely Fair Scheduler (CFS)

Approximate fair scheduling

- Run each thread once per schedule latency (SL)
- Weighted time slice: SL * Wi / (Sum of all Wi)
- Too many threads?
 - Lower bound on smallest time slice
 - Schedule latency = lower bound * (# threads)

Picking the next process

Pick proc with minimum virtual runtime so far

- Virtual runtime: task->vruntime += executed time / Wi
- Example
 - P1: 1 ms burst per 10 ms (schedule latency)
 - P2 and P3 are CPU-bound
 - All processes have the same weight (1)



Finding proc with minimum runtime fast

Red-black tree

- Balanced binary search tree
- Ordered by vruntime as key
- O(IgN) insertion, deletion, update, O(1): find min



- Tasks move from left of tree to the right
- min_vruntime caches smallest value
- Update vruntime and min_vruntime
 - When task is added or removed
 - On every timer tick

Notable implementation details

Integer table of nice-level to weight

- static const int prio_to_weight[40] (kernel/sched/sched.h)
- Nice level changes by $1 \rightarrow 10\%$ weight
- 🗅 cgroup
 - Fairness between users & apps, rather than threads
 - cgroup's vruntime == sum of its threads' vruntimes
- Upper bound on vruntime difference
 - New thread gets max vruntime in the RQ
 - When thread wakes up, its vruntime >= min_vruntime
- Load balancing based on many factors

Load Balancing in CFS

Goal: Equalize load across cores

What is load? The amount of work on all cores of the machine. This is different from evening out the number of threads.

Example: if a user runs 1 CPU-intensive task and 10 tasks that mostly sleep, CFS might schedule the 10 mostly sleeping tasks on a single core.

How? Work stealing periodically from other cores (default every 4msec)

Can steal multiple tasks at a time to balance load quickly.

Load Balancing in CFS

Goal: Equalize load across cores

Goal 2: Maximize locality

Wake-up/Creation:

- 1-to-1: Schedule the woken-up task nearby
- 1-to-many: Spread the tasks

Stealing:

- try to steal work more frequently from cores that are "close" to them than from cores that are "remote"
- hierarchical load balancing

Load Balancing in Practice



(a) Slow "perfect" load balancing (b) CFS

$\text{CFS no more} \rightarrow \text{EEVDF}$

Earliest Eligible Virtual Deadline First became the default scheduler in Linux 6.6

Fairness

Process lag = weighted average of every task's vruntime - process current weighted vruntime

Weight based on nice value

A: vruntime=10 \rightarrow lag = -10 B: vruntime=30 \rightarrow lag = 10

$\text{CFS no more} \rightarrow \text{EEVDF}$

Interactivity CFS uses a static minimum time slice

EEVDF time slice = base time slice / weight (weight depends on nice value)

Deadline = vruntime + time slice + lag

Assume Tasks A, B with same vruntime and lag and Wa > Wb

- Task A: Deadline = vruntime + lag + short time slice (due to high weight)
- Task B: Deadline = vruntime + lag + longer time slice (due to low weight)

EEVDF picks Task A to run

Hierarchical scheduling class in Linux

pick_next_task() in kernel/sched/core.c essentially does this:

```
for (class = sched_class_highest;
        class != NULL;
        class = class->next;)
{
        p = class->pick_next_task(rq);
        if (p)
            return p;
}
// The idle class should always have a runnable task
```

BUG();

struct sched class (up to kernel 5.8)

- const struct sched class rt sched class = {
 - = &fair sched class, .next
 - .enqueue task

 - .yield task

 - .check preempt curr
 - .pick next task

.set next task

- = check preempt curr rt,
- = yield task rt,
- .dequeue task = dequeue task rt,

= enqueue task rt,

.put prev task = put prev task rt,

= pick next task rt,

= set next task rt,

Array of sched_class

- Sched classes are now arranged in an array by linker scripts
 - include/asm-generic/vmlinux.lds.h:



• for_class_range() macros in 5.8:

```
#define for_class_range(class, _from, _to) \
    for (class = (_from); class != (_to); class = class->next)
```

• for_class_range() macros in 5.10:

```
#define for_class_range(class, _from, _to) \
    for (class = (_from); class != (_to); class--)
```

Runqueue data structures

- struct rq(kernel/sched/sched.h)
 - Main per-CPU runqueue data structure
 - Contains per-sched_class runqueues: cfs_rq, rt_rq, etc.

• **struct sched_entity** (include/linux/sched.h)

- sched_<class>_entity for each sched_class (except that sched_entity is for cfs)
- Member of task_struct, one per each sched_class

•task_struct.sched_class

- Pointer to the current sched_class for the task
- sched_setscheduler() syscall changes process's sched_class